

Application Note AN025

Designing for Wide-range Multi-input PoE PD Systems such as IP Cameras

Rev 1.2 August 2018

TABLE OF CONTENTS

TABLE OF CONTENTS	2
FIGURES AND TABLES	2
ABOUT APPLICATION NOTE AN080	2
GENERAL DESCRIPTION	
LOCAL POWER OPTIONS - 24VAC RECTIFICATION AND 12VDC	
PRIORITY SCHEMES FOR MULTIPLE INPUTS – POE VS. LOCAL POWER Power Mode Selection Using the LVMODE Pin on the AS1138	4
WIDE-INPUT PD SYSTEM SCHEMATICS	6
TRANSFORMER SELECTION FOR LOWER-VOLTAGE LOCAL POWER SOURCE	9 10
SUMMARY	
CONTACT INFORMATION	11
IMPORTANT NOTICES	11
Legal Notice	11
Reference Design Policy	11
Life Support Policy	11
Substance Compliance	11

FIGURES AND TABLES

Figure 1 - IP Cameras	3
Figure 2 - Rectifier Circuit	3
Figure 3 - LVMODE Implementation	4
Figure 4 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with Local Power Given Priority	
Figure 5 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with PoE Power Given Priority with PMOS Switch	7
Figure 6 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with PoE Power Given Priority with PNP Switch	8
Figure 7 - Theoretical Power Transformer Primary-Current Waveform	10
Table 1 - LVMODE Configuration	5
Table 2 - Approved LVMODE Transformers	10

ABOUT APPLICATION NOTE AN025

Application Note AN025 describes how to implement a universal PoE PD system design supporting a wide range of input options, including PoE (36V-57V), 24VAC and 12VDC local/auxiliary power inputs. With minimal bill-of-materials changes only, a single Kinetic Technologies-based design can seamlessly support 13W/30W and 802.3af/at designs operating over a wide input voltage range of 9.5V-57V.

These guidelines should be used in conjunction with the datasheet and reference design. The design guide provides information for adapting the reference design to a customer's system. If there are any questions of concerns, please contact the Kinetic Technologies applications team through your sales contact or <u>info@kinet-ic.com</u>.

Refer to <u>http://www.kinet-ic.com</u> for further details on these and other Kinetic Technologies components.



GENERAL DESCRIPTION

Power over Ethernet (PoE) has found increasing use in a variety of new powered-network appliances. One example of such growth is in the area of IP cameras (see Figure 1). This growth has been driven by the convenience and economy of connecting security cameras into a LAN infrastructure using conventional Unshielded Twisted Pair (UTP) cabling.

The IEEE 802.3at standard defines a means for delivering combined Ethernet data and up to 13W (Type 1 PD) of power over UTP cable, which is commonly used for simple security camera applications. A Type 2 PD increases the power level to 25. The higher power delivery allows the deployment of surveillance cameras with pan-tilt-zoom (PTZ) capability and housing temperature control for outdoor environments.

Although network cabling is economical and convenient to install, security cameras are commonly designed to take advantage of established local power delivery infrastructure, such as 24VAC or 12VDC rails. There is also the situation where not all Ethernet connections are PoE. As such, there is much benefit to utilizing PoE PD designs that can support a variety of input power options, including PoE, 24VAC and 12VDC.

By providing the capability to use a local power adapter, the usage environment for networked appliances is much broader. For instance, a local power connection still allows a PoE surveillance camera to be installed in a setting where PoE has not yet been deployed. Such flexibility allows the use of the existing LAN infrastructure while also providing a ready migration path to PoE.

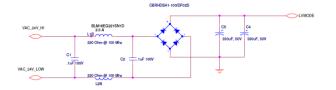
The AS1138 integrated circuit is designed to handle a wide range of input voltages (i.e. 9.5V to 57V) with a single system design.



LOCAL POWER OPTIONS - 24VAC RECTIFICATION AND 12VDC

Local power options can be made compatible by using a rectifier circuit to convert 24VAC to ~32VDC (as shown in Figure 2). In such a way, both 24VAC inputs and 12VDC inputs can utilize the same channel for the local power path.





If either a 24VAC input <u>or</u> a 12VDC input will be used (but not plugged in at the same time), then either input can be applied to the same input terminals of the rectifier circuit.

On the other hand, if both the 24VAC input and 12VDC input can be simultaneously connected to the system, then an additional diode "OR"ing scheme should be implemented at the output of the diode bridge to merge in the 12VDC option.



PRIORITY SCHEMES FOR MULTIPLE INPUTS - POE VS. LOCAL POWER

Power Mode Selection Using the LVMODE Pin on the AS1138

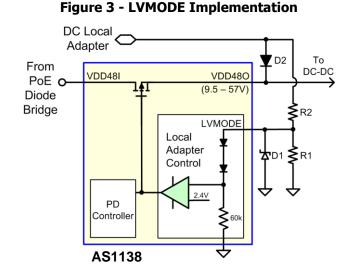
For the AS1138, the LVMODE feature may be used in applications where the PD appliance is designed to draw power from either the Ethernet cable or an external DC localpower adapter. The LVMODE pin is a current-mode input pin, with low and high thresholds as defined in the parametric tables of the AS1138 datasheet. LVMODE is asserted when the input current exceeds the I_{IH} threshold, and is deasserted when the input current is below the I_{IL} threshold. If LVMODE operation is not desired, the LVMODE pin should be connected to GND.

For the systems shown in this application note, primary-side power merging of input sources is shown. For details on configuring other power insertion options (e.g. primary-side vs. secondary-side merging), please refer to "AN006 - Using PoE PD with a Local Power Supply, Rev. 1.0".

Priority Given to Local Power

Figure 3 shows a simplified internal implementation and external application circuit required to use the LVMODE feature. When power is applied at the localadapter input, the AS1138 enters Local Voltage Mode. This opens the internal Hot-Swap FET switch and reduces the UVLO threshold while the DC-DC converter is in operation.

In this configuration, local power always takes priority, even in the presence of PoE power, regardless of their relative voltages. If local power is removed, the device will exit Local Voltage Mode operation and PoE power will be used if available.



Local power, whether from a 12VDC source or a rectified 24VAC source, is inserted at the VDD480 node through an external diode (D2). Use of a low reverse-leakage diode is recommended (<350uA, at worst case temperature). This ensures that when there is no local power, PoE voltage at the VDD480 node will not falsely pull up the LVMODE pin due to high reverse leakage through the diode.

An appropriate ratio of R2 and R1 resistors should be used to ensure proper operation across all supply voltages. Table 1 lists appropriate choices of R2 and R1 resistors to work with a variety of popular local adapter DC voltages. Though a common value of R2 and R1 can be used across the whole range of local supply voltages from 9.5V to 57V, using different value pairs, per the table below, will minimize power dissipation. The maximum input voltage at the LVMODE pin should not exceed 6V. A Zener diode (D1) is recommended to clamp the voltage at the pin.

Because the input current at the LVMODE pin defines its state, it is not recommended to drive other circuits or components directly from the LVMODE node (such as an LED) that might draw current. LEDs or currentabsorbing components may be driven directly from the Local Supply pin.



Local Voltage Range	Recommended Local Adapters	R2	R1		
9.5V-57V	12V, 18V	2.74kΩ	4.02kΩ		
20V-57V	24V, 30V	11.3kΩ	4.02kΩ		
32.4V-57V	36V, 48V	20.0kΩ	4.02kΩ		
Diode D1: 5.6V Zener, BZT56V Diode D2: S3B (100V/3A, worst-case reverse leakage <250uA), use of a low reverse-leakage diode with worst-case reverse leakage under high temperature <350uA is recommended.					

Table 1 - LVMODE Configuration

The AS1138 internal DC-DC controller is designed to operate with input voltages of 9.5V-57V, to allow applications to take advantage of the LVMODE feature. Besides configuring the device for operation from a local power source, the external power transformer must also be designed to ensure proper operation across the complete input range. Please contact Kinetic Technologies for system design assistance.

Figure 4 shows the detailed reference schematic for a system implementation supporting PoE, 24VAC and 12VDC inputs, with the local VAC_24V/VDC_12V adapter always given priority.

Priority Given to PoE Power

For systems desiring that priority be given to PoE power when both local power and PoE power are present, an alternate circuit scheme can be used.

The logic in the detailed schematic shown in Figure 5 is designed to give priority to PoE power. If power is applied through the PoE input and the local adapter, the power to the converter always comes from the PoE source. The PoE input drives the gate of the P-channel MOSFET, Q6, so whenever PoE power is applied, Q6 turns off, and the LVMODE pin is pulled low through R7. This keeps the internal Hot-Swap FET (between VDD48I and VDD48O) on, thereby applying power from the PoE input to the converter by overdriving the lower local-adapter voltage.

When there is no power applied through the PoE input, the gate of Q6 is pulled low, causing the P-channel MOSFET (Q6) to turn on, thereby shutting off the internal Hot-Swap FET with power being applied to the converter through the VAC_24V or VDC_12V adapter.

Diode D13 blocks the voltage from LVMODE, as the body diode of the internal Hot-Swap FET allows a direct current path from VDD480 (anode) to VDD48I (cathode). It should be noted that the PoE input voltage must exceed the local power input voltage for this circuit to operate correctly.



WIDE-INPUT PD SYSTEM SCHEMATICS

For complete system reference schematics and associated bills of materials, please contact Kinetic Technologies.

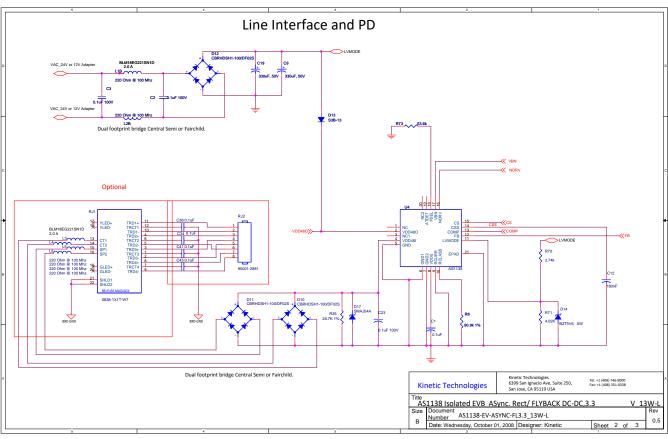
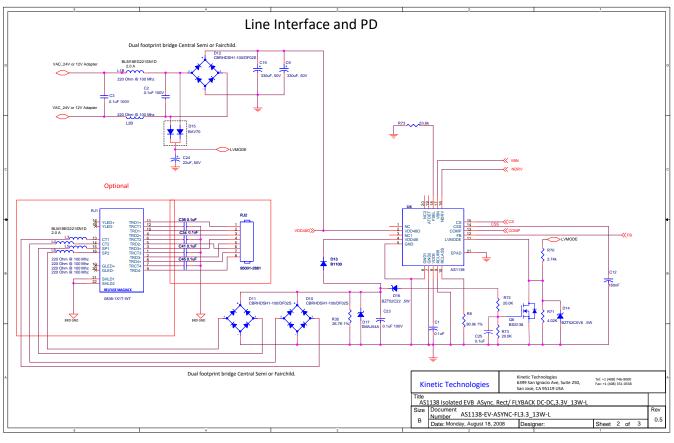


Figure 4 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with Local Power Given Priority



Figure 5 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with PoE Power Given Priority with PMOS Switch





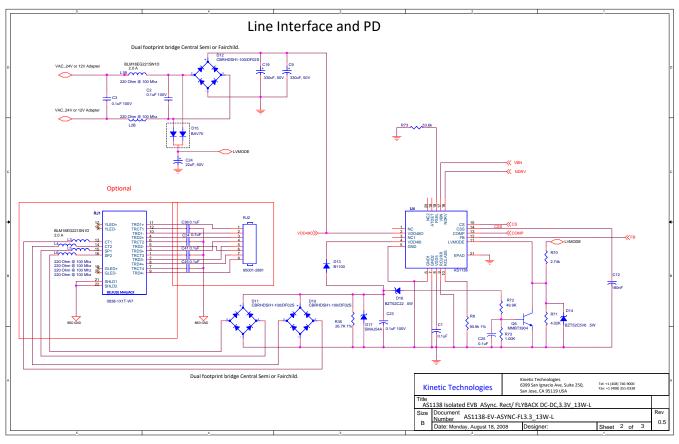


Figure 6 - Reference Schematic for 3-input System (PoE, 24VAC and 12VDC) with PoE Power Given Priority with PNP Switch



Vqs(abs max) - 2V.

of IMEAN to minimize AC loss.

auidelines:

(CCM).

In addition, use the following transformer selection

• Make sure the negative voltage on the

• Set the minimum duty cycle, D_{MIN}, to 26-28%.

Synchronous FET drive winding is less than

Set the current ripple to approximately 20-30%

Design for the minimum desired output current

at the boundaries of Discontinuous Conduction

Mode (DCM) and Continuous Conduction Mode

I_{IN} = input current at DC-DC converter**T** = switching period of power FET

power transformer (normally one diode drop higher than DC-DC converter output voltage

IMEAN = mean primary current during

 DмIN = duty cycle at minimum load, maximum input voltage
 Vs = voltage level at secondary of

"ON" period

N = primary turns

voltage Ns = secondary turns

voltage

Ns

L_P = primary inductance

IPEAK = primary peak current

VINMAX = maximum input operating

for 5V gate drive VSYN-NEGMAX = absolute max of synchronization

Ns2 = Synch. FET secondary turns. Set

FET negative gate drive voltage ΔI = ripple current (change of primary

current during the "ON" period)

V_{INMIN} = minimum DC-DC converter input

TRANSFORMER SELECTION FOR LOWER-VOLTAGE LOCAL POWER SOURCE

If the local power voltage and PoE voltage are the same, then there are no additional issues in the transformer design. However, if the local source voltage is significantly lower than the PoE line (<32V), then special consideration must be taken in the transformer circuit design. The primary inductance and turns ratio of the transformer impact the duty cycle for the DC-DC converter.

Fundamentally, the signal at the switching node of the transformer follows the relationship:

$$I_{MEAN} := \frac{P_{OUT}}{V_{INMIN} \cdot \eta \cdot D_{MAX}}$$

$$I_{\scriptscriptstyle MEAN}\coloneqq I_{\scriptscriptstyle IN}\cdot \frac{T}{T_{\scriptscriptstyle ONCAL}}$$

$$D_{MIN} \coloneqq V_{S} \cdot \frac{N}{\left(V_{S} \cdot N + V_{INMAX} \cdot N_{S}\right)}$$

$$\Delta I := \frac{2 \cdot I_{OUT-MIN}}{1 - D_{MAX}} \cdot \frac{N_S}{N}$$

 $\frac{N_s}{N} := \frac{V_s \cdot (1 - D_{MAX})}{D_{MAX} \cdot V_{INMIN}}$

$$V_{SYN-NEGMAX} := \frac{V_{INMAX} \cdot N_{S2}}{N}$$

$$I_{PEAK} \coloneqq I_{MEAN} + \frac{\Delta I}{2}$$

$$L_{S} := \frac{V_{S} \cdot (1 - D_{MAX}) \cdot T}{\Delta I}$$

$$L_P := L_S \cdot \left(\frac{N}{N_S}\right)^2$$

IOUT-MIN = minimum output current

(transformer conduction transition from DCM into CCM)

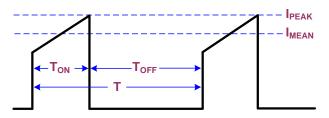
Ls = secondary inductance of winding

- **D**_{MAX} = maximum desired duty cycle
- **F**_{sw} = operating frequency (switching frequency), equal to 1/T
 - η = Converter efficiency (estimated)

Pout = Output power



Figure 7 - Theoretical Power Transformer Primary-Current Waveform



Below, Table 2, is a list of transformers suitable for lower-voltage local power designs that have passed Kinetic Technologies' performance tests. Note: This is not a complete list, and omissions are not intended to suggest the unsuitability of other vendors' products.

Prior to designing, please contact Kinetic Technologies for the most recent list of optimized and qualified transformers.

Vendor contact information

- Coilcraft, Inc. <u>http://www.coilcraft.com</u>
- Halo Electronics, Inc.
 <u>http://www.haloelectronics.com</u>
- Pulse Engineering, Inc. http://www.pulseeng.com
- Würth Elektronik Group
 <u>http://www.we-online.com</u>

Additional Reference Material

- IEEE P802.3at[™] Specification
- AS1138 Datasheet
- AN006 Using PoE PD with a Local Power Supply
- AN024 AS1138 Universal Reference Design

KINETIC PART #	APPLICATION	LVMODE OPERATING VOLTAGE RANGE	VENDOR	TRANSFORMER PART #
AS1138	3.3V13W Sync Flyback	10-57	Coilcraft	HA3585-BL
AS1138	3.3V13W Async Flyback	10-57	Halo	TGP13-S032EP13LF
AS1138	5V13W Sync Flyback	10-57	Halo	TGSP-P025EFD15LF
AS1138	5V13W Async Flyback	10-57	Coilcraft	HA3871-AL
AS1138	3.3V30W Sync Flyback	10-57	Coilcraft	HA3809-AL
AS1138	5V30W Sync Flyback	10-57	Halo	TGSP-P032EFD20LF
AS1138	5V30W Sync Flyback	10-57	Coilcraft	HA3715-DL

Table 2 - Approved LVMODE Transformers

SUMMARY

Use of local power adapters can increase the versatility of PoE PD appliances. Such adapters allow operation within legacy Ethernet environments until PoE is deployed. In addition to configuration flexibility, multiple independent power sources can also provide redundancy for mission-critical applications.

The Kinetic Technologies AS1138 integrated circuit delivers a "one size fits all" PoE PD solution, enabling easy forward and backward design compatibility as well as maximum flexibility in supporting a wide range

of applications (802.3af/at, 13W/30W and 9.5-57Vin). With a single design enabling such a wide range of applications with only a few component assembly changes, time to market is greatly improved, especially as a viable "copy-paste" design approach can be employed.

Finally, designers can proceed with confidence that Kinetic Technologies has a thorough understanding of transformer design and can readily assist customers with the transformer selection and optimization process.



CONTACT INFORMATION

Kinetic Technologies 6399 San Ignacio Ave, Suite 250, San Jose, CA 95119 USA Tel: (408) 746-9000 Fax: (408) 351-0338 Email inquiries: <u>info@kinet-ic.com</u> Website: http://www.kinet-ic.com

IMPORTANT NOTICES

Legal Notice

Copyright © 2008 Kinetic Technologies. All rights reserved. Other names, brands and trademarks are the property of others. Kinetic Technologies assumes no responsibility or liability for information contained in this document. Kinetic reserves the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or services without notice. The information contained herein is believed to be accurate and reliable at the time of printing.

Reference Design Policy

This document is provided as a design reference and Kinetic Technologies assumes no responsibility or liability for the information contained in this document. Kinetic reserves the right to make corrections, modifications, enhancements, improvements and other changes to this reference design documentation without notice.

Reference designs are created using Kinetic Technologies's published specifications as well as the published specifications of other device manufacturers. This information may not be current at the time the reference design is built. Kinetic Technologies and/or its licensors do not warrant the accuracy or completeness of the specifications or any information contained therein.

Kinetic does not warrant that the designs are production worthy. Customer should completely validate and test the design implementation to confirm the system functionality for the end use application.

Kinetic Technologies provides its customers with limited product warranties, according to the standard Kinetic Technologies terms and conditions.

For the most current product information visit us at http://www.kinet-ic.com.

Life Support Policy

LIFE SUPPORT: KINETIC' PRODUCTS ARE NOT DESIGNED, INTENDED, OR AUTHORIZED FOR USE AS COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS. NO WARRANTY, EXPRESS OR IMPLIED, IS MADE FOR THIS USE. AUTHORIZATION FOR SUCH USE SHALL NOT BE GIVEN BY KINETIC, AND THE PRODUCTS SHALL NOT BE USED IN SUCH DEVICES OR SYSTEMS, EXCEPT UPON THE WRITTEN APPROVAL OF THE PRESIDENT OF KINETIC FOLLOWING A DETERMINATION BY KINETIC THAT SUCH USE IS FEASIBLE. SUCH APPROVAL MAY BE WITHHELD FOR ANY OR NO REASON.

"Life support devices or systems" are devices or systems which (1) are intended for surgical implant into the human body, (2) support or sustain human life, or (3) monitor critical bodily functions including, but not limited to, cardiac, respirator, and neurological functions, and whose failure to perform can be reasonably expected to result in a significant bodily injury to the user. A "critical component" is any component of a life support device or system whose failure to perform can be reasonably expected to result or perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

Substance Compliance

With respect to any representation by Kinetic Technologies that its products are compliant with RoHS, Kinetic Technologies complies with the Restriction of the use of Hazardous Substances Standard ("RoHS"), which is more formally known as Directive 2002/95/EC of the European Parliament and of the Council of 27 January 2003 on the restriction of the use of certain hazardous substances in electrical and electronic equipment. To the best of our knowledge the information is true and correct as of the date of the original publication of the information. Kinetic Technologies bears no responsibility to update such statements.

